



Characterization, Propagation and Analysis of Aleatory and Epistemic Uncertainty in the 2008 Performance Assessment for the Proposed Repository for Radioactive Waste at Yucca Mountain, Nevada

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Waste for Yucca Mountain



Commercial Spent Nuclear Fuel:
63,000 MTHM (~7500 waste packages)



DOE & Naval Spent Nuclear Fuel:
2,333 MTHM
(~400 naval waste packages)
(DSNF packaged with HLW)

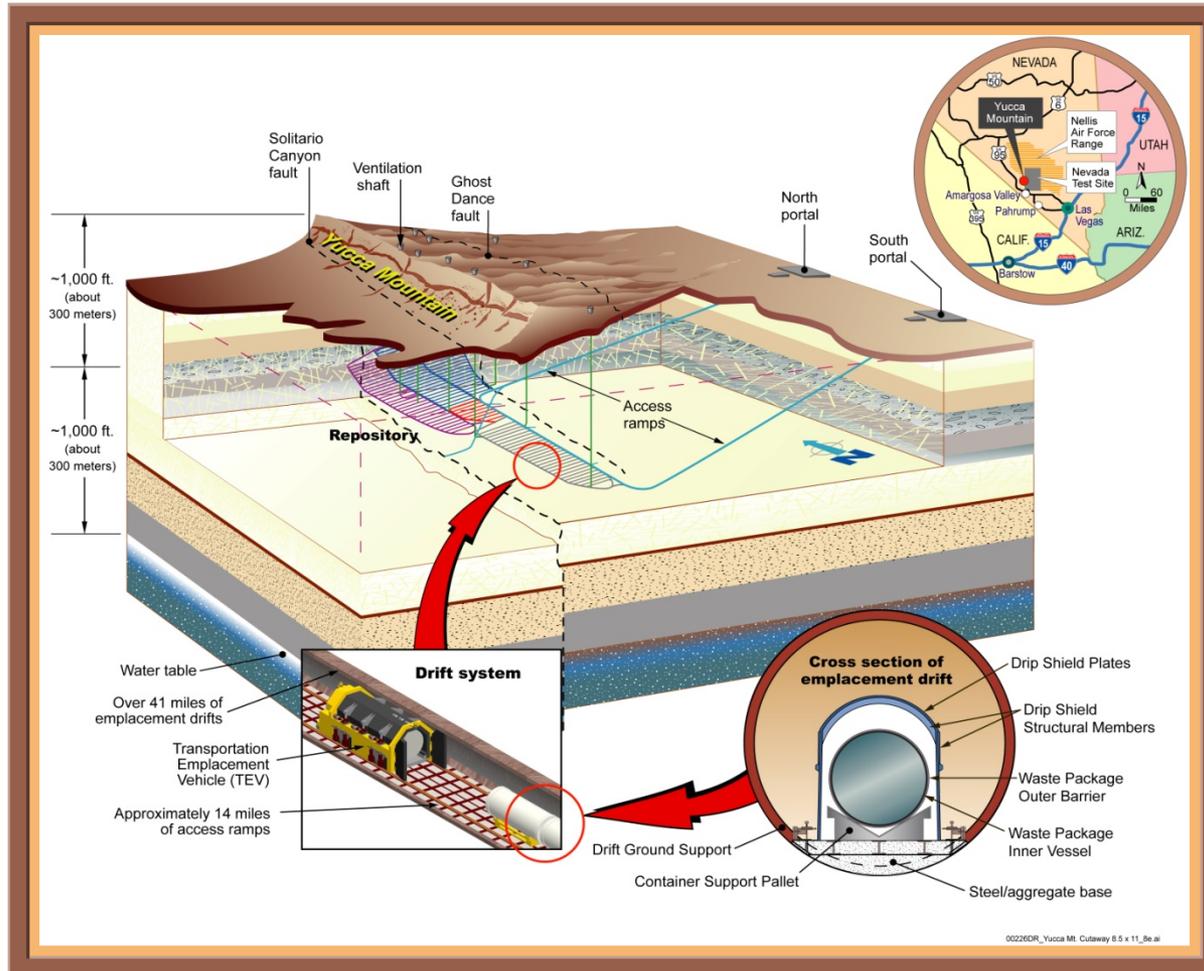


DOE & Commercial High-Level Waste:
4,667 MTHM
(~3000 waste packages of co-disposed DSNF and HLW)



DSNF: Defense Spent Nuclear Fuel
HLW: High Level Radioactive Waste
MTHM: Metric Tons Heavy Metal

Proposed Repository at Yucca Mountain





Post-Closure Regulatory Requirements for proposed Yucca Mountain repository

- 10 CFR 63 and 40 CFR Part 197
Maximum value of mean dose to the reasonably maximally exposed individual (RMEI) over time interval $[0, 10^4 \text{ yr}]$ less than 15 mrem/yr
- Maximum value of mean dose to the RMEI over time interval $[10^4, 10^6 \text{ yr}]$ less than 100 mrem/yr
- Take uncertainties and gaps in knowledge into account
- Requirements lead to Performance Assessment (PA) that
 - Computes measures of performance (e.g. mean dose)
 - Accounts for and quantifies uncertainty in measures of performance



Sources of Uncertainty

Lack of knowledge about the future state of the system
probabilities of disruptive events

Incomplete data

for example, limited hydrologic data from test wells

Spatial variability and scaling issues

data may be available from small volumes (for example, porosity measurements from core samples), but may be used in the models to represent large volumes

Measurement error

usually only a very minor source of uncertainty compared to uncertainty from incomplete data

Alternative conceptual models



Categories of Uncertainty

Aleatory Uncertainty

- Inherent randomness in events that could occur in the future
- Alternative descriptors: irreducible, stochastic, intrinsic, type A
- Examples:
 - *Time and size of an igneous event*
 - *Time and size of a seismic event*

Epistemic uncertainty

- Lack of knowledge about appropriate value to use for a quantity assumed to have a fixed value
- Alternative descriptors: reducible, subjective, state of knowledge, type B
- Examples:
 - *Spatially averaged permeabilities, porosities, sorption coefficients, ...*
 - *Rates defining Poisson processes*



Four Questions Underlying PA

1. What events and processes can take place at the facility?
2. How likely are these events or processes?
3. What are the consequences of these events or processes?
 - Kaplan and Garrick (1979) “risk triplet”
4. How certain are the answers to the first 3 questions?



Mathematical Entities Underlying the YM PA

EN1: Probability space characterizing what can happen in the future

- Answers “What can happen” and “How likely”
- Provides formal characterization of aleatory uncertainty

E.G. Assumption that igneous event occurrence is a Poisson process

EN2: Mathematical models for predicting consequences

- Answers “What are the consequences”

E.G. Flow and Transport Models

EN3: Probability space characterizing uncertainty in TSPA inputs

- Basis for answering “How certain are the answers to the other three questions”
- Provides formal characterization of epistemic uncertainty

E.G. Distribution assigned to rate for a Poisson process

Scenarios for the YM PA

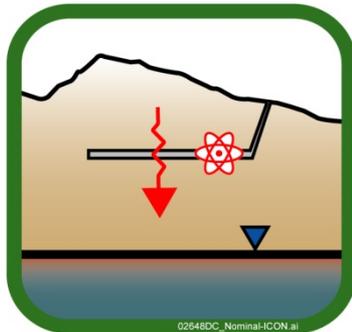
Possible events are screened (10^{-8} yr⁻¹ minimum) then grouped by event type to form four scenario classes (divided into seven modeling cases by effect of event on disposal system)

Nominal Scenario Class

- Nominal Modeling Case (included with Seismic Ground Motion for 1,000,000-yr analyses)

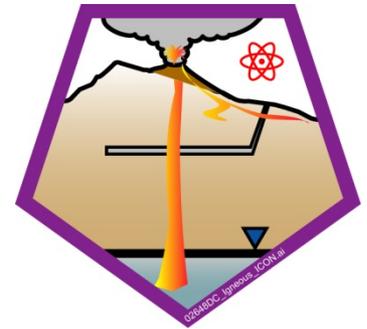
Early Failure Scenario Class

- Waste Package Modeling Case
- Drip Shield Modeling Case



Igneous Scenario Class

- Intrusion Modeling Case
- Eruption Modeling Case



Seismic Scenario Class

- Ground Motion Modeling Case
- Fault Displacement Modeling Case





EN1: Probability Space for Aleatory Uncertainty

Characterizes uncertainty in occurrence of future events

Define a vector that describes an individual future \mathbf{a}

$$\mathbf{a} = [nEW, nED, nII, nIE, nSG, nSF, \mathbf{a}_{EW}, \mathbf{a}_{ED}, \mathbf{a}_{II}, \mathbf{a}_{IE}, \mathbf{a}_{SG}, \mathbf{a}_{SF}]$$

where

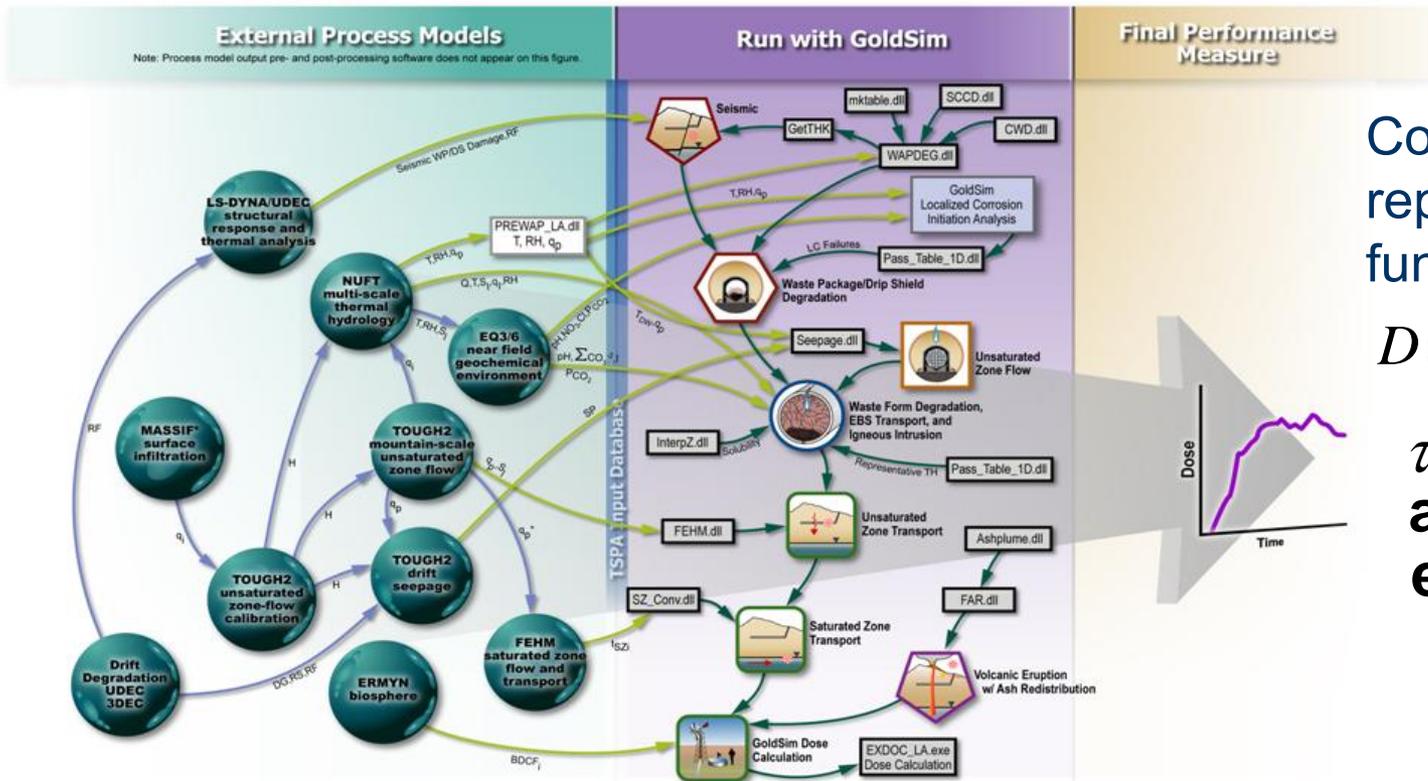
- nEW = number of early WP failures
- nED = number of early DS failures
- nII = number of igneous intrusive events
- nIE = number of igneous eruptive events
- nSG = number of seismic ground motion events
- nSF = number of fault displacement events
- \mathbf{a}_{EW} = vector defining nEW early WP failures
- \mathbf{a}_{ED} = vector defining nED early DS failures
- \mathbf{a}_{II} = vector defining nII igneous intrusive events
- \mathbf{a}_{IE} = vector defining nIE igneous eruptive events
- \mathbf{a}_{SG} = vector defining nSG seismic ground motion events
- \mathbf{a}_{SF} = vector defining nSF fault displacement events

Form the set \mathcal{A} of all such vectors (description of all possible futures)

$$\mathcal{A} = \left\{ \mathbf{a} : \mathbf{a} = [nEW, nED, nII, nIE, nSG, nSF, \mathbf{a}_{EW}, \mathbf{a}_{ED}, \mathbf{a}_{II}, \mathbf{a}_{IE}, \mathbf{a}_{SG}, \mathbf{a}_{SF}] \right\}$$

Characterize each element of \mathbf{a} with a probability distribution

EN2: Models for Estimating Consequences



Conceptually represented by a function

$$D(\tau | \mathbf{a}, \mathbf{e})$$

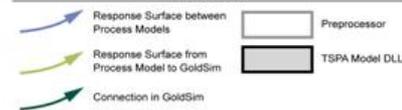
- τ time
- \mathbf{a} future
- \mathbf{e} model inputs

Output Parameters

f_s	Fraction of WPs with Seeps	q_p	Percolation Flux	q_i	Infiltration Flux	H	Hydrologic Properties
EBS	Engineered Barrier System	NO_3	Nitrate Concentration	DG	Drift Geometry	SP	Seepage Parameters
Q	Seep Flow Rate	T	Temperature	Cl	Chloride Concentration	RS	Rock Strength
Q_s	Evaporation Rate	RH	Relative Humidity	I	Ionic Strength	RF	Rockfall Size and Number
pH		S_l	Liquid Saturation	t_{sz}	Saturated Zone Transport Time		
ΣCO_3^{2-}	Carbonate Concentration	X_A	Air Mass Fraction	BDC _F	Biosphere Dose Conversion Factor		
P_{CO_2}	Partial Pressure of CO ₂	q_l	Liquid Flux	q_g	Gas Flux		

*Note: q_p derived from INFIL model

Legend



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EN3: Probability Space for Epistemic Uncertainty

- 392 epistemically uncertain analysis inputs
- $\mathbf{e} = [e_1, e_2, \dots, e_{392}]$, $\mathcal{E} = \{ \mathbf{e} : \mathbf{e} = [e_1, \dots, e_{392}] \}$
- Example elements of \mathbf{e}

ASHDENS - Tephra settled density (kg/m³). *Distribution:* Truncated normal. *Range:* 300 to 1500. *Mean:* 1000. *Standard Deviation:* 100.

IGRATE - Frequency of intersection of the repository footprint by a volcanic event (yr⁻¹). *Distribution:* Piecewise uniform. *Range:* 0 to 7.76E-07.

INFIL - Pointer variable for determining infiltration conditions: 10th, 30th, 50th or 90th percentile infiltration scenario (dimensionless). *Distribution:* Discrete. *Range:* 1 to 4.

MICPU239 - Groundwater biosphere dose conversion factor (BDCF) for ²³⁹Pu in modern interglacial climate ((Sv/year)/(Bq/m³)). *Distribution:* Discrete. *Range:* 3.49E-07 to 2.93E-06. *Mean:* 9.55E-07.

SZFISPVO - Flowing interval spacing in fractured volcanic units (m). *Distribution:* Piecewise uniform. *Range:* 1.86 to 80.

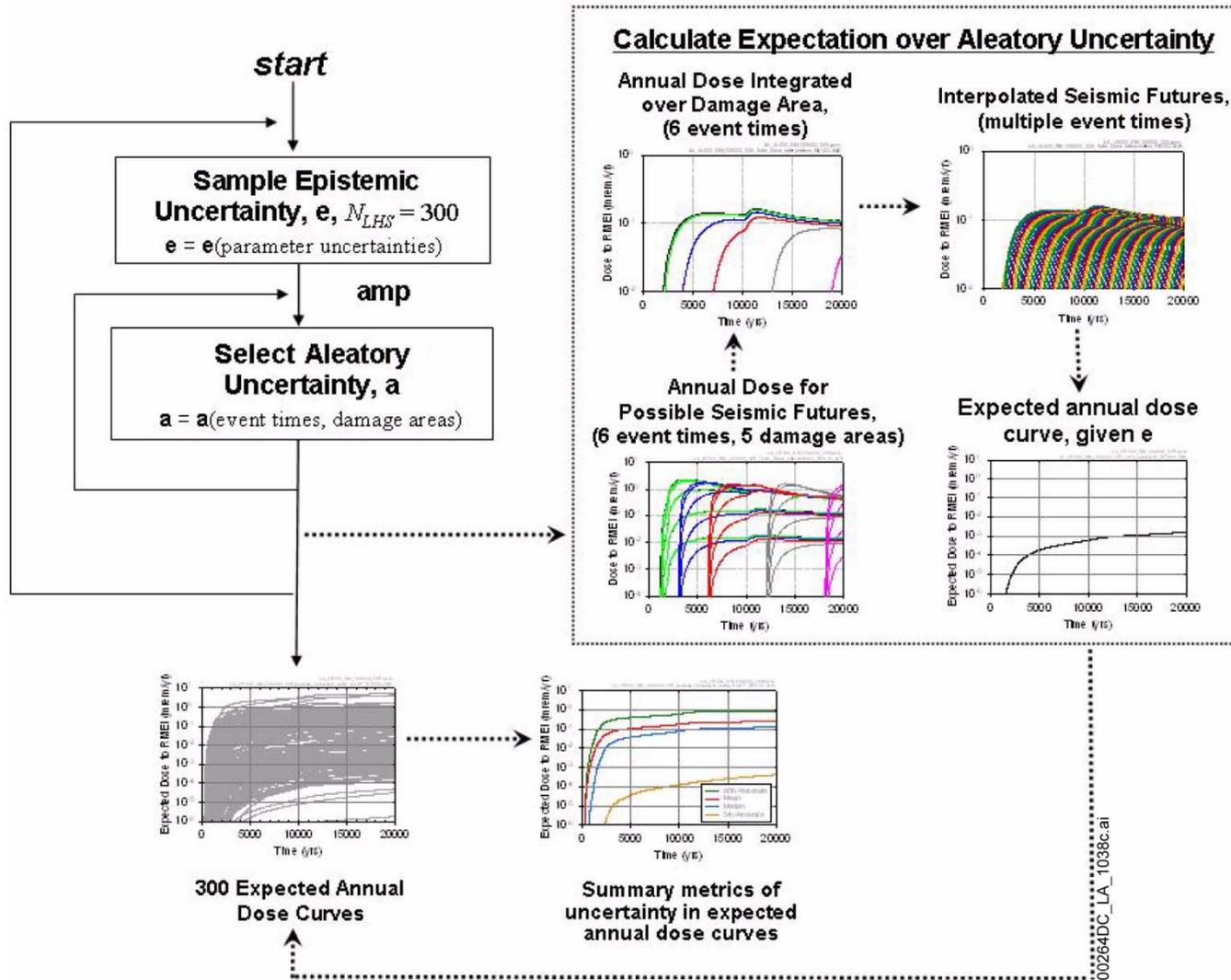


Conceptual Calculation of Total Mean Dose

- Regulation requests “mean” values of dose to a reasonably maximally exposed individual
- Uncertainty in future events \mathbf{a} and in model inputs \mathbf{e} lead to a distribution of estimates of dose
- Calculation proceeds in three stages:

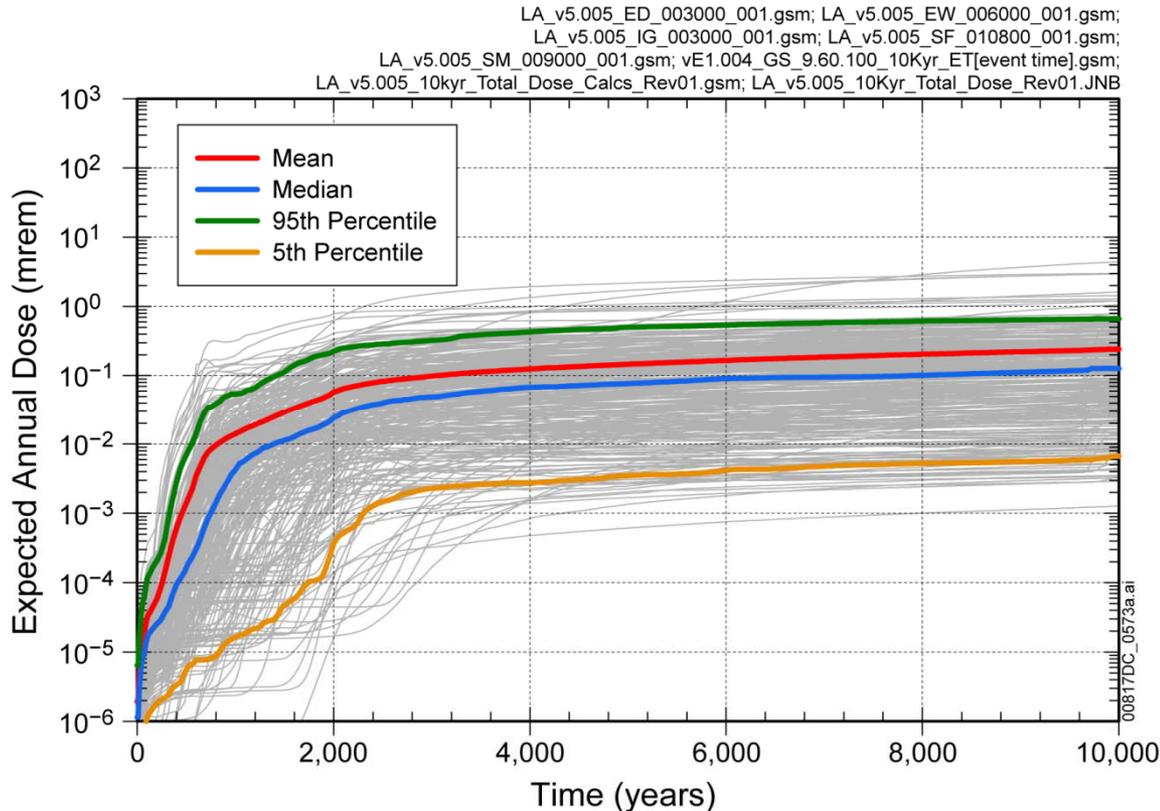
$$\begin{aligned}\bar{\bar{D}}(\tau) &= E_E \left[E_A \left(D(\tau | \mathbf{a}, \mathbf{e}) \right) \right] \\ &= \int_E \left[\int_{\mathcal{A}} D(\tau | \mathbf{a}, \mathbf{e}) d_A(\mathbf{a} | \mathbf{e}) dA \right] d_E(\mathbf{e}) dE \\ &\cong \int_E \left[\int_{\mathcal{A}} \left\{ \sum_{MC} D_{MC}(\tau | \mathbf{a}, \mathbf{e}) \right\} d_A(\mathbf{a} | \mathbf{e}) dA \right] d_E(\mathbf{e}) dE \\ &= \int_E \sum_{MC} \left[\int_{\mathcal{A}} D_{MC}(\tau | \mathbf{a}, \mathbf{e}) d_A(\mathbf{a} | \mathbf{e}) dA \right] d_E(\mathbf{e}) dE\end{aligned}$$

Illustration of Calculation of Expected Dose



YM PA Results

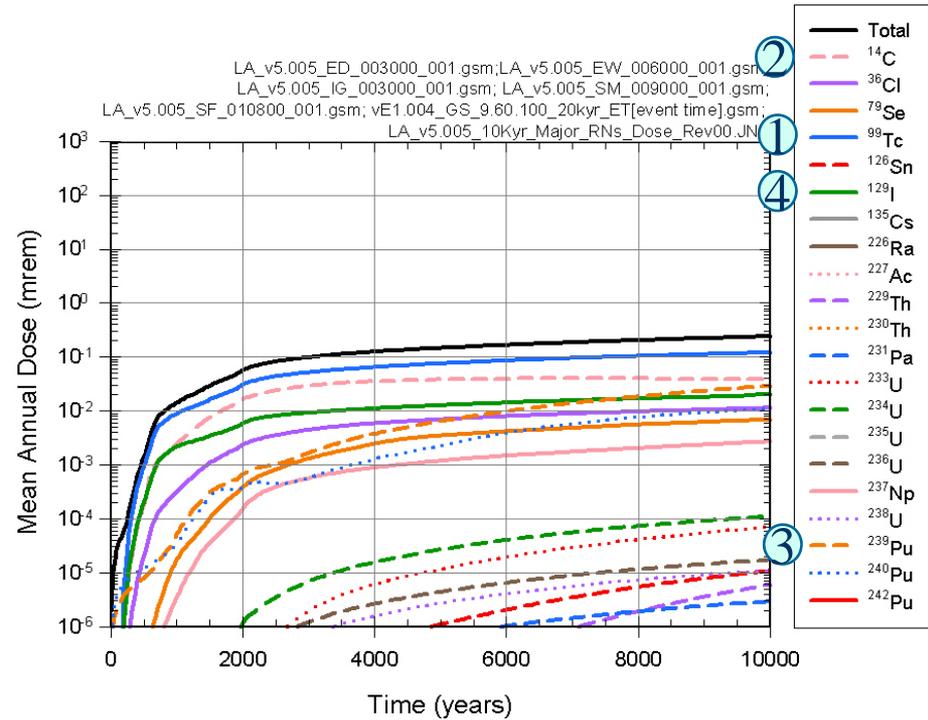
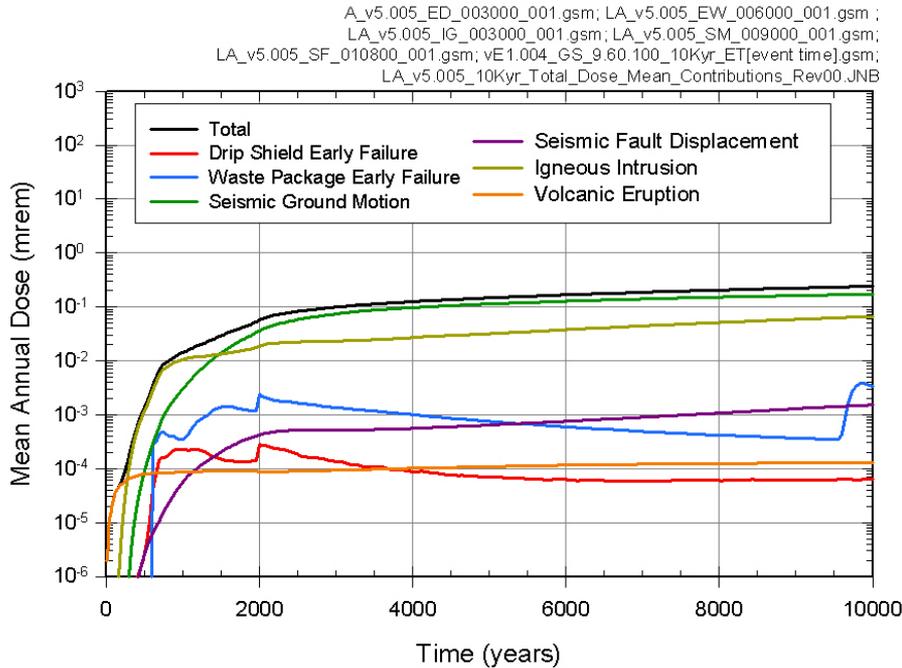
Individual Protection Standard: 10,000 yr



Four questions:

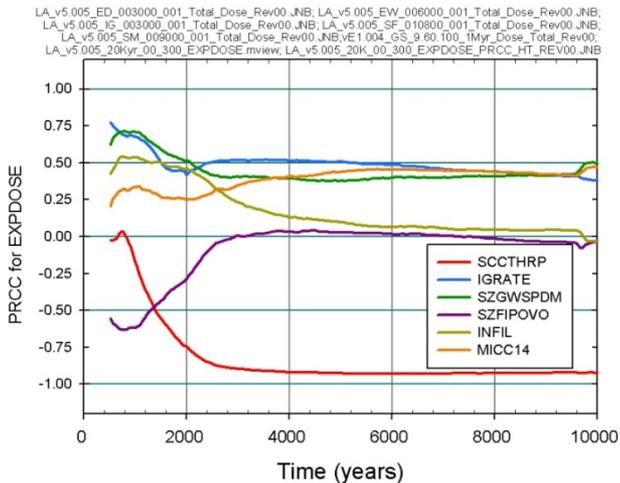
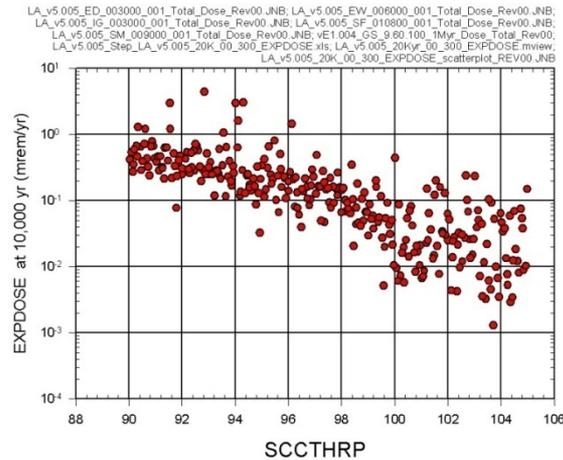
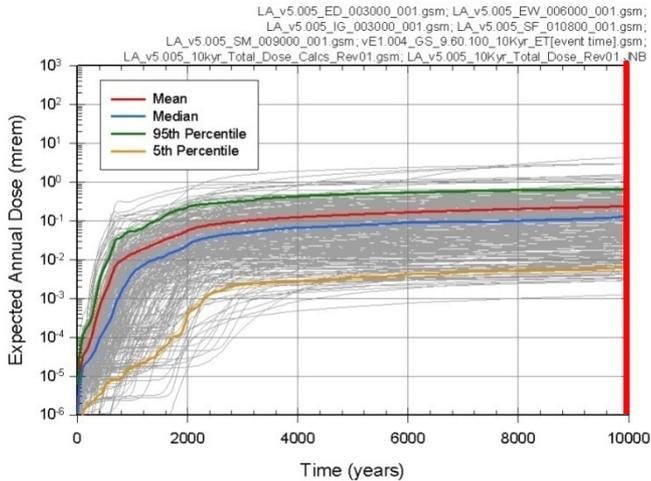
1. What determines the shape of these curves?
2. What determines the magnitude of total mean dose?
3. What determines the uncertainty in total expected dose?
4. Are these results stable?

Total Mean Dose Contributions By Modeling Case and Radionuclide



Note: Contribution from Nominal Modeling Case is zero within 10,000 years

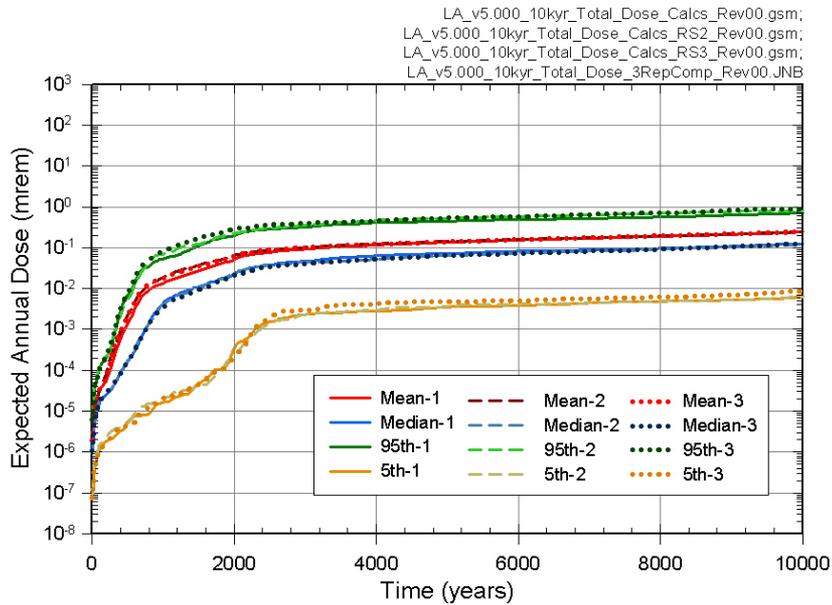
Uncertainty in Total Expected Dose



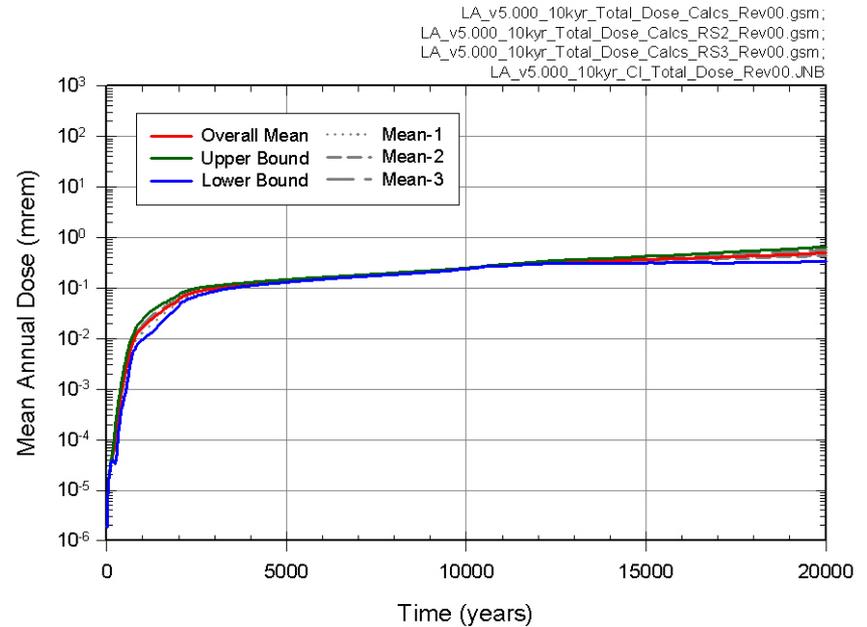
Step	Variable	R ²	SRRC
1	SCCTHRP	0.69	-0.82
2	IGRATE	0.73	0.22
3	SZGWSPDM	0.76	0.17
4	MICTC99	0.78	0.14
5	WFDEGEXF	0.79	0.11
6	MICC14	0.80	0.10
7	UZGAM	0.81	-0.10
8	WDGCUA22	0.81	-0.07
9	HLWGRNDS	0.82	-0.08
10	CSWFA0AC	0.82	-0.07

SCCTHRP – stress threshold for SCC initiation (90 to 105% of yield strength)
IGRATE – frequency of igneous events
SZGWSPDM – logarithm of uncertainty factor in groundwater specific discharge

Stability of Total Dose



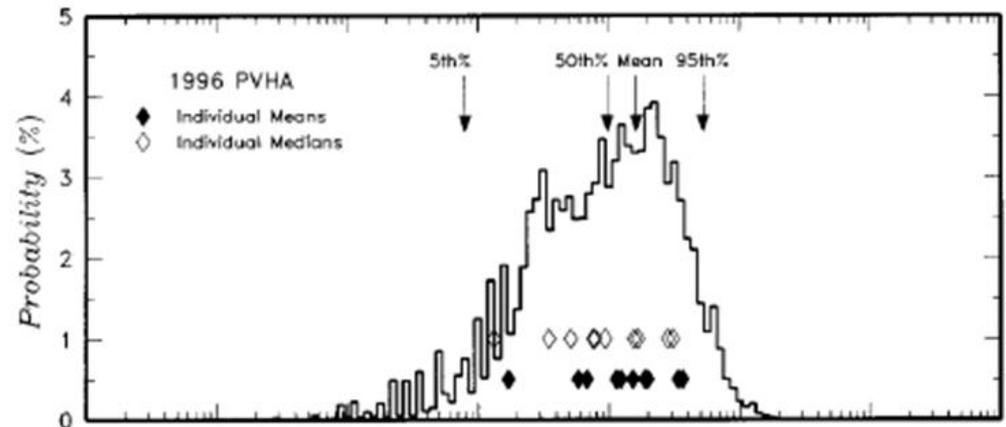
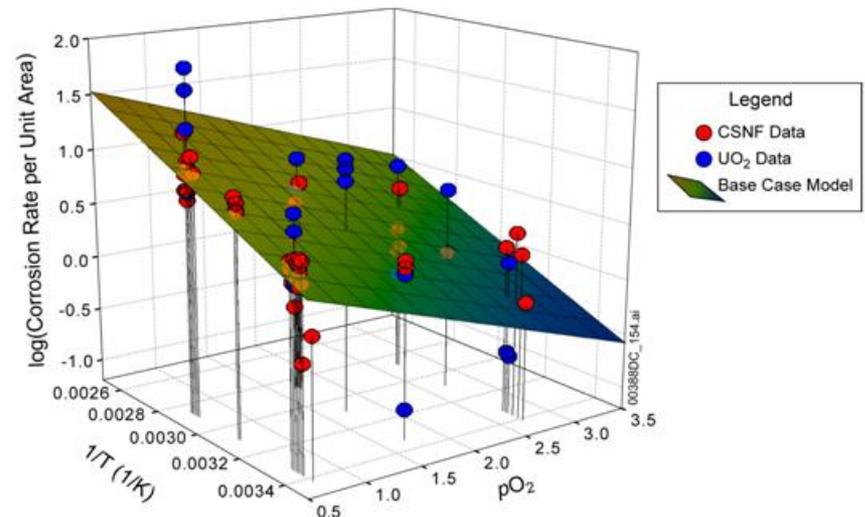
Replicated sampling demonstrates that sample size is sufficient



Confidence interval illustrates precision of estimate of total mean dose

Quantifying Uncertainty

- Uncertainty in inputs (aleatory or epistemic) results from expert judgment
 - Empirical distribution
 - Model fit to data
 - Calibration with uncertainty range
- In some cases formal elicitation procedures are used
- Uncertainty in outputs results from propagating uncertain inputs through models





Addressing Uncertainty in Models

- Uncertainty in models arises from:
 - an incomplete knowledge of the behaviour of engineered systems, physical processes, or site characteristics,
 - representation of features, events and processes using simplified mathematical models,
 - the inexact implementation of mathematical models in numerical form and in computer codes.
- Addressed primarily by comparing alternative models
 - Generally, one model is selected that overstates radionuclide releases (as compared to alternative models)
 - In some cases, several models are implemented and selected by means of an uncertain pointer variable
- Other schemes exist (e.g., Bayesian updating) but not use for YM PA was not practical



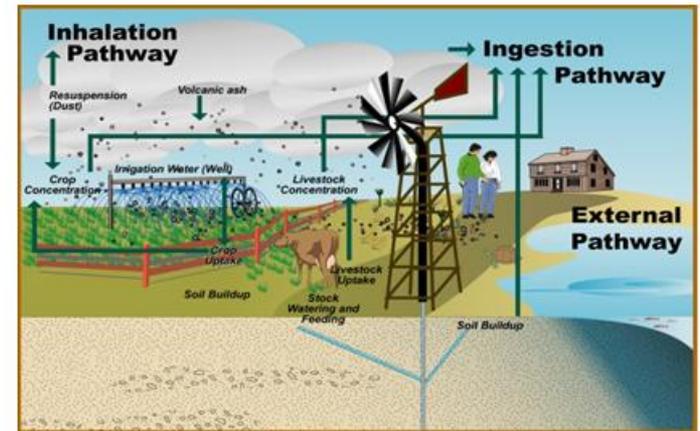
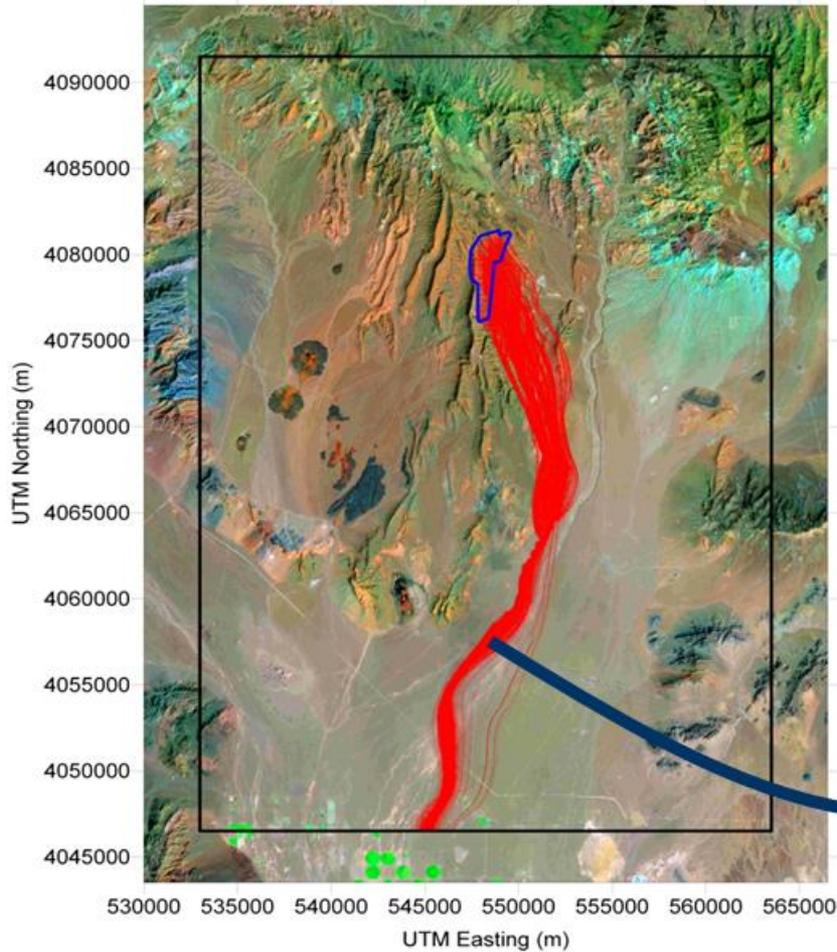
Summary

- Probabilistic structure used for performance assessment of a proposed nuclear waste disposal facility
- Analysis accounts for uncertainty in
 - Future events (aleatory)
 - State-of-knowledge as basis for modeling site performance (epistemic)
- Distinction between types of uncertainty aids in identifying source of uncertainty and its characterization



Backup Slides

Estimating Dose to Hypothetical Future Humans



Modeled groundwater flow paths and hypothetical exposure pathways