Next Generation of PV Inverter Technologies
PHOTOVOLTAIC AND DISTRIBUTED SYSTEMS INTEGRATION
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Outline

PV System
- PV system designs and capabilities
- Changes to Codes and Standards
- Utility interconnection requirements

Reliability impacts
- Implementation of these functions
- Mitigation capabilities
- applications

Summary
PV System Design Reliability Challenges

- Many variations in PV system designs and implementations and each have different reliability concerns. Residential and commercial designs have similar requirements but typically involve different methods of implementation.

  - Residential PV systems
    - Are typically roof mounted systems – additional safety requirements
    - Dc-dc converters, charge controllers, and string single/multi-dc input inverters
    - Micro-inverters

  - Commercial/Utility PV system
    - Roof mount (big box) installation
    - ground mount (smart combiner box)
    - Large pad mount (multi-unit devices)
Changing Codes and Standards

NEC 2011 690.11 Arc Fault Protection (Direct Current): as stated
PV systems with dc sources circuits, dc output circuits, or both, on or penetrating a building operating at a PV system maximum voltage of 80 volts or greater shall be protected by a listed (dc) arc-fault circuit interrupter, PV type, or other system components listed to provide equivalent protection.

NEC 2014 690.11 Arc Fault Protection (Direct Current): [ROP4-251*]
Photovoltaic systems with dc source circuits, dc output circuits, or both, operating at a PV system maximum system voltage of 80 volts or greater, shall be protected by a listed (dc) arc-fault circuit interrupter, PV type, or other system components listed to provide equivalent protection. *proposed change

NEC 2011 690.35 (C): Ground-Fault Protection
All photovoltaic sources and output circuits shall be provided with a ground-fault protection device or system that complies with (1) through (3):
(1) Detects a ground fault.
(2) Indicates that a ground fault has occurred
(3) Automatically disconnects all conductors or causes the inverter or charge controller connected to the faulted circuit to automatically cease supplying power to output circuits

NEC 2011 690.35 (C): Ground-Fault Protection [ROP 4–302]*
(1) Determine the PV input circuit has isolation prior to export of current
* proposed change
The high penetration of distributed energy resources has initiated the revision of the utility interconnection standard IEEE 1547, which allows the distributed resources to have a more significant contribution to the area EPS.

P1547a Draft Standard for Interconnecting Distributed Resources with Electric Power Systems – Amendment 1

The three main sections of IEEE 1547 the amendment addresses are:

- **Clause 4.1.1 Voltage regulation**

  “The DR shall not actively regulate the voltage at the PCC. Coordination with and approval of, the area EPS and DR operators, shall be required for the DR to actively participate to regulate the voltage by changes of real and reactive power. The DR shall not cause the Area EPS service voltage at other Local EPSs to go outside the requirements of ANSI C84.1-2006 1995, Range A.”
The second section the amendment addresses is:

- **Clause 4.2.3 Voltage** *(Response to area EPS abnormal voltage conditions)*

When any voltage is in a range given in Table 1, the DR shall cease to energize the Area EPS within the clearing time as indicated. Under mutual agreement between the EPS and DR operators, other static or dynamic voltage trip levels and clearing time trip settings\(^1\) shall be permitted.

<table>
<thead>
<tr>
<th>Default settings(^a)</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Voltage range (% of base voltage(^b))</strong></td>
<td>Clearing time (s)</td>
</tr>
<tr>
<td>V $&lt;$ 45</td>
<td>0.16</td>
</tr>
<tr>
<td>45 $&lt;$ V $&lt;$ 60</td>
<td>1</td>
</tr>
<tr>
<td>60 $&lt;$ V $&lt;$ 88</td>
<td>2</td>
</tr>
<tr>
<td>110 $&lt;$ V $&lt;$ 120</td>
<td>1</td>
</tr>
<tr>
<td>V $&gt;$ 120</td>
<td>0.16</td>
</tr>
</tbody>
</table>

\(^a\) Under mutual agreement between the EPS and DR operators, other static or dynamic voltage and clearing time trip settings shall be permitted\(^1\)

\(^b\) Base voltages are the nominal system voltages stated in ANSI C84.1-2006, Table 1. \(^1\)
The third section the amendment addresses is:

- **Clause 4.2.4 Frequency** *(Response to area EPS abnormal frequency conditions)*

  Under mutual agreement between the EPS and DR operators, other static or dynamic frequency and clearing ¹ time trip settings shall be permitted.

<table>
<thead>
<tr>
<th>Function</th>
<th>Default settings</th>
<th>Ranges of adjustability&lt;sup&gt;(a)&lt;/sup&gt;</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Frequency (Hz).</td>
<td>Clearing time (s)</td>
</tr>
<tr>
<td>UF1</td>
<td>57</td>
<td>0.16</td>
</tr>
<tr>
<td>UF2</td>
<td>59.5</td>
<td>20</td>
</tr>
<tr>
<td>Power reduction&lt;sup&gt;(b)&lt;/sup&gt;</td>
<td>60.3</td>
<td>10</td>
</tr>
<tr>
<td>OF1</td>
<td>60.5</td>
<td>20</td>
</tr>
<tr>
<td>OF2</td>
<td>62</td>
<td>0.16</td>
</tr>
<tr>
<td></td>
<td>56 – 60</td>
<td>0 – 10</td>
</tr>
<tr>
<td></td>
<td>56 – 60</td>
<td>0 – 300</td>
</tr>
<tr>
<td></td>
<td>60 - 64</td>
<td>0 - 300</td>
</tr>
<tr>
<td></td>
<td>60 - 64</td>
<td>0 – 300</td>
</tr>
<tr>
<td></td>
<td>60 - 64</td>
<td>0 - 10</td>
</tr>
</tbody>
</table>

<sup>(a)</sup> Unless otherwise specified, default ranges of adjustability shall be as stated.

<sup>(b)</sup> When used, the DR power reduction function settings shall be as mutually agreed to by the area EPS and DR operators.
Reliability Concerns implementing Voltage Regulation Capabilities

Autonomous implementation of Volt/Var function

- Voltage is monitored at point of common coupling (PCC)
- Watt or Var priority is determined by controls
- VA/Watt/Var level is dependent on voltage level and ac current limit

Volt-Var Controls

- V1-V4 are all adjustable parameters
- Qmax is determined based on the amount of kVA capability “left over” after the real power needs are satisfied (i.e., real power is prioritized)
- Working to determine what ramp capabilities are achievable while maintaining stability
Autonomous implementation of Volt/Var function (watt priority)

Stimulus: Limits adhere to IEEE 1547

- Increased inverter losses with volt/var control

Conduction Losses

$$\hat{P}_{\text{loss,cond}} \approx \kappa_1 I + \kappa_2 I^2$$

Switching losses

$$\hat{P}_{\text{loss,sw}} \approx \frac{1}{6} f_{sw} VI \left( T_{\text{off}} + T_{\text{on}} \right)$$

$$I_{\text{rms}} = \left( P^2 + Q^2 \right)^{1/2}$$

$$3V_{\text{rms}}$$

These losses require additional heat mitigation capability to sustain sufficient design margins on critical components.
The high penetration of DER has lead to the desire/requirement for the distributed resources to ride through momentary sag/surge in voltage and frequency. Presently the proposed change in the interconnection standard does not have a ride through requirement. This may change.

No ride through requirement

Proposed must ride through requirement with must trip level out of way for expanded ride through. *Many curves exist*
Low Voltage Ride Through Implementation

The result of ride through in voltage allows devices to stay on line and assist the EPS meet their load demands during critical conditions. Consequence of implementing this capability are perturbations on voltage and currents.

Dc voltage and ac current perturbations

Dc voltage and re-synchronization perturbations
Summary

New features driven by code and standard changes add safety and value to the PV system installations. These features do add the need to quantify the effectiveness over time and to document the susceptibility to degradation in performance.

NEC changes/proposed changes

- DC arc fault detection - integrated, external, or combiner box (communications)
- Ground fault – residual current monitoring, RISO measurement

IEEE 1547 Utility interconnection standard changes

- VRT/FRT capability
- Volt/Var
- Frequency/Watt
Thank You

Questions?